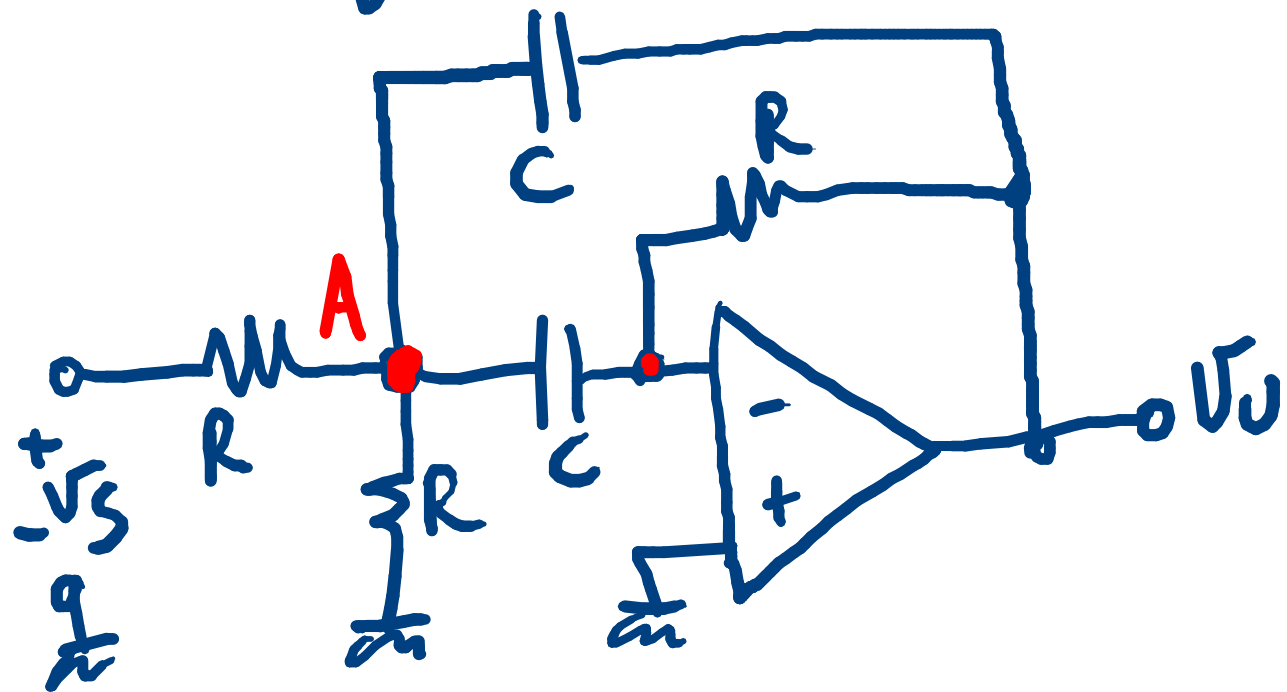


Delayannis



$$\begin{cases} C_s (v_u - v_A) + \frac{(v_s - v_A)}{R} - \frac{v_A}{R} - C_s v_A = 0 \\ v_u = -R C_s v_A \Rightarrow \frac{v_u}{R C_s} = v_A \end{cases}$$

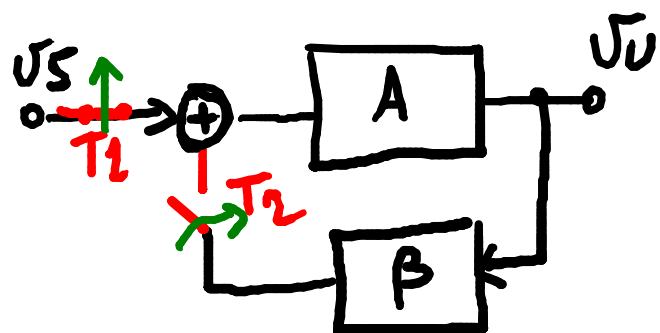
$$C_s \left(v_u + \frac{v_u}{R C_s} \right) + \left(v_s + \frac{v_u}{R C_s} \right) \frac{1}{R} + \frac{v_u}{R^2 C_s} + \frac{v_u}{R} = 0$$

$$C_s v_u + \frac{v_u}{R} + \frac{v_s}{R} + \frac{v_u}{R^2 C_s} + \frac{v_u}{R^2 C_s} + \frac{v_u}{R} = 0$$

$$R^2 C_s^2 v_u + R C_s v_u + R C_s v_s + v_u + v_u + R C_s v_u = 0$$

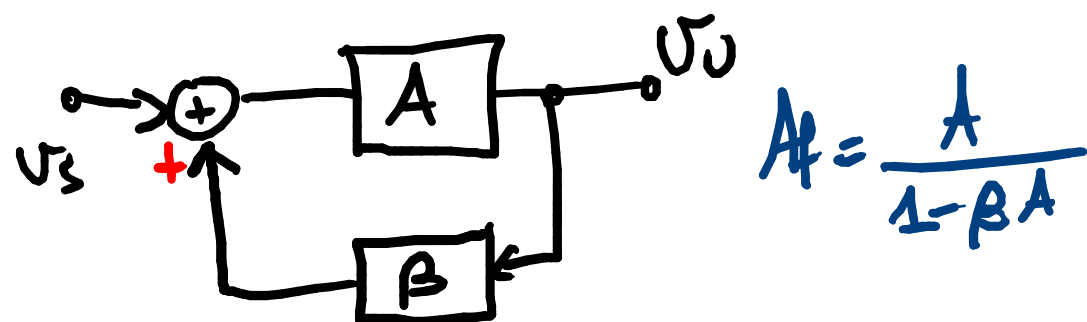
$$[R^2 C_s^2 s^2 + 2 R C_s + 2] v_u = -R C_s v_s$$

$$\frac{v_u}{v_s} = \frac{-R C_s}{R^2 C_s^2 s^2 + 2 R C_s + 2}$$

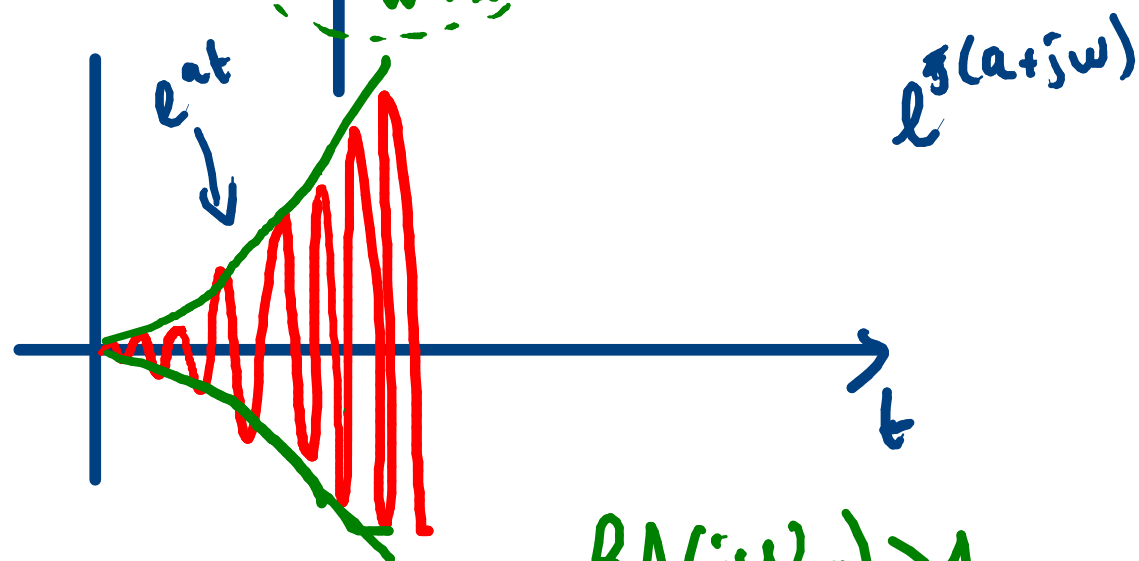
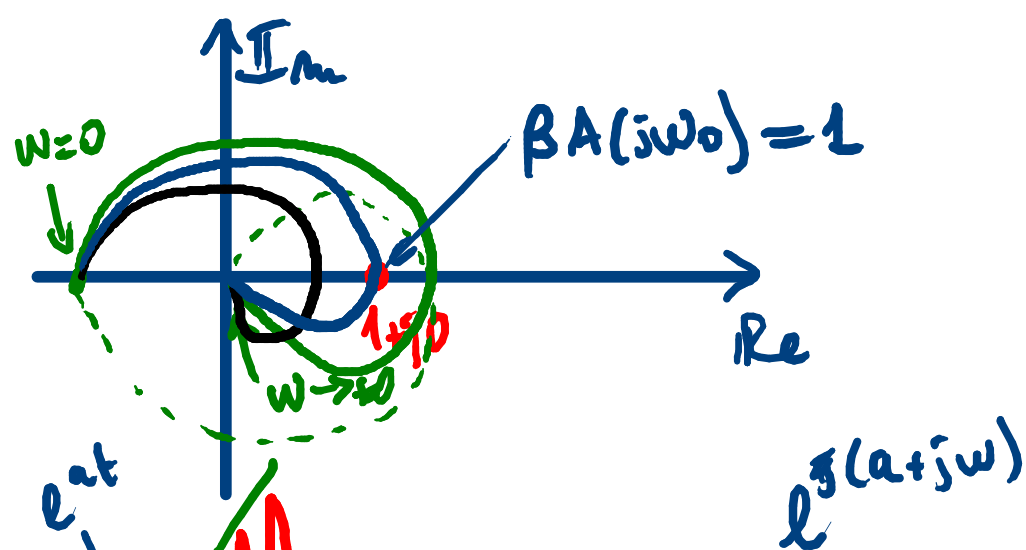


$\beta A = 1$ BARKHAUSEN

$$\begin{cases} |BA(j\omega_0)| = 1 \\ \angle BA(j\omega_0) = \phi \end{cases}$$



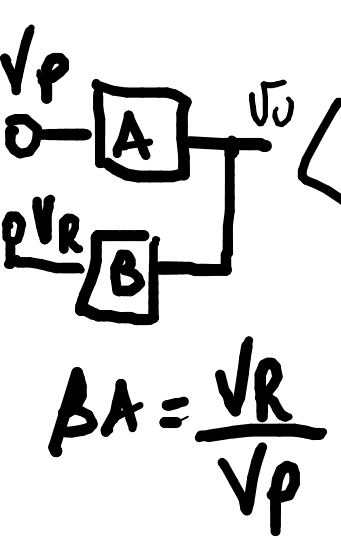
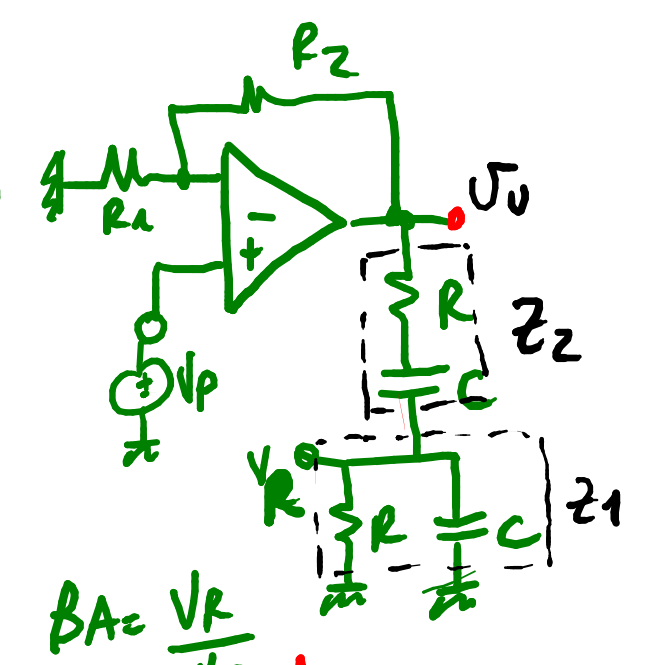
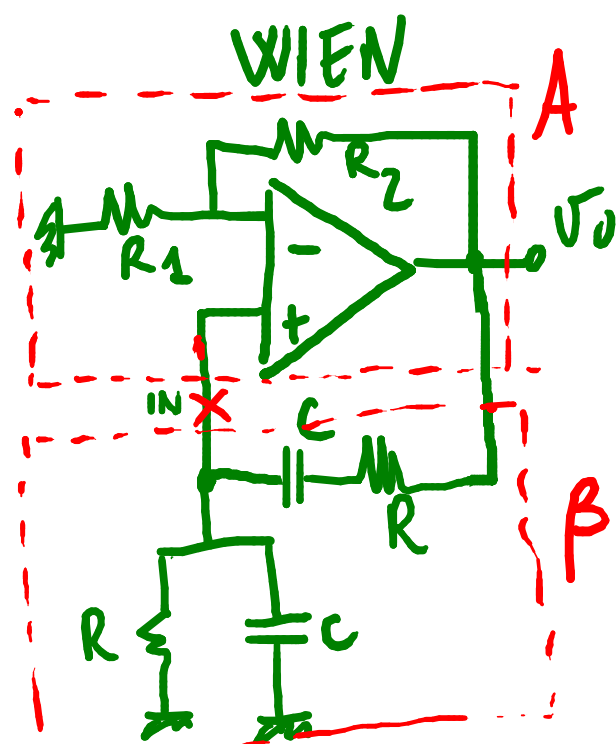
$$A_f = \frac{A}{1 - \beta A}$$



$$\beta A(j\omega_E) > 1$$

$$\begin{cases} |\beta A(j\omega_E)| > 1 \\ \angle \beta A(j\omega_E) = \phi \end{cases}$$

$$\angle \beta A(j\omega_E) = \phi$$



$$BA = \frac{V_R}{V_P}$$

$$BA = \frac{V_R}{V_P} A_V$$

$$V_0 = \left(1 + \frac{R_2}{R_1}\right) V_p$$

$$V_R = V_0 \cdot \frac{z_1}{z_1 + z_2}$$

$$z_2 = R + \frac{1}{Cs} = \frac{Rcs + 1}{Cs}$$

$$z_1 = \frac{\frac{R}{Cs}}{R + \frac{1}{Cs}} = \frac{R}{Rcs + 1}$$

$$BA(s) = \frac{V_R}{V_P} = \frac{\frac{R}{Rcs + 1}}{\frac{R}{Rcs + 1} + \frac{Rcs + 1}{Cs}} A_V = \frac{A_V R C s}{Rcs + (Rcs + 1)^2}$$

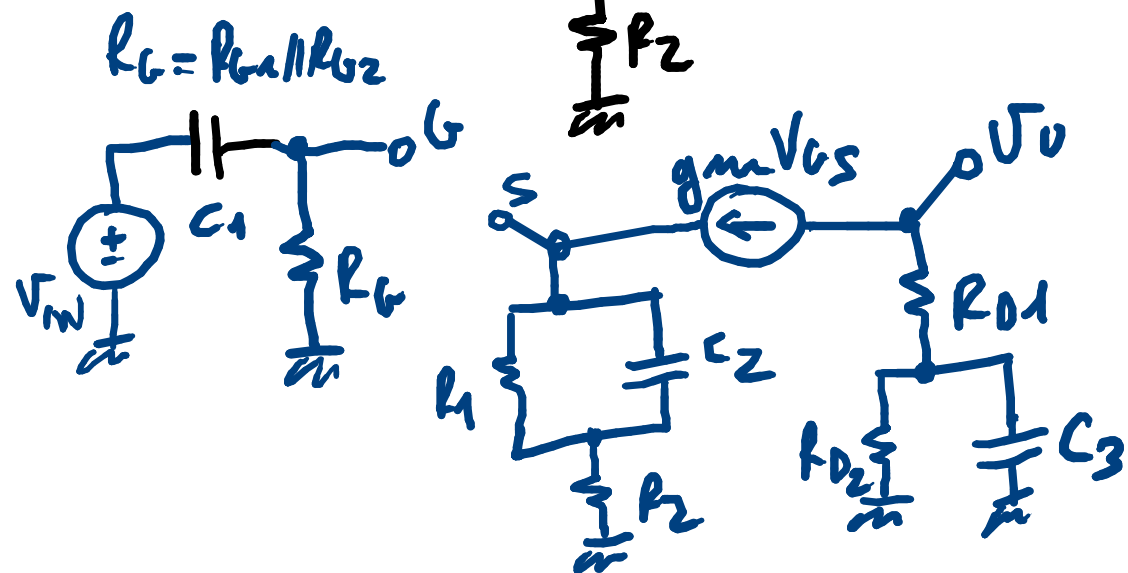
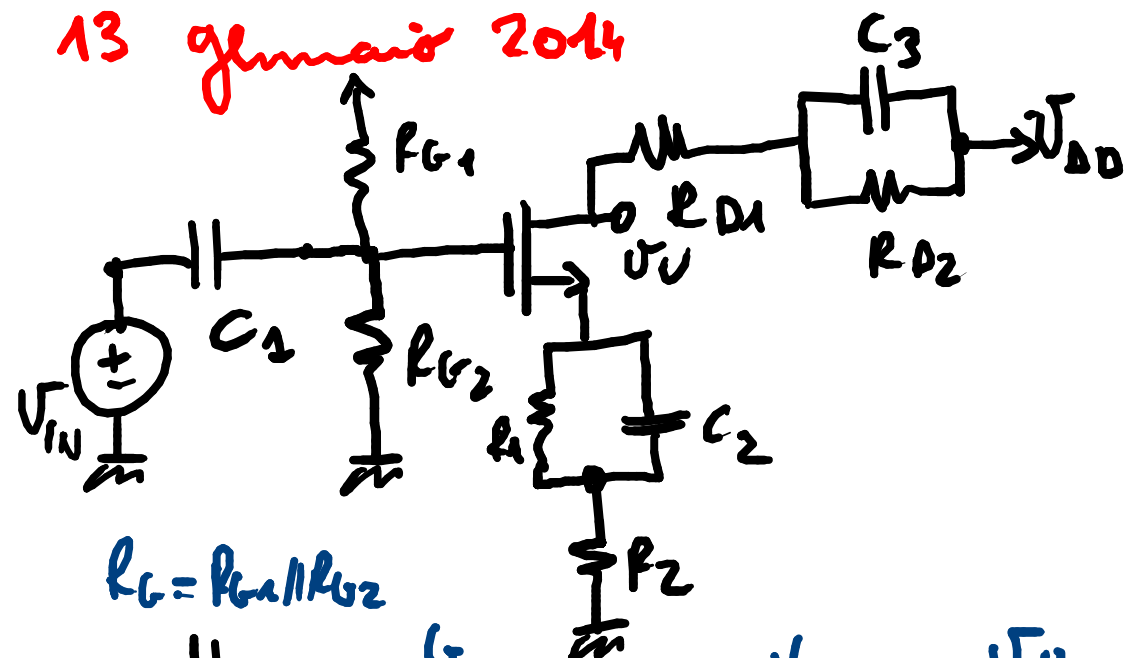
$$BA(s) = \frac{Rcs A_V}{R^2 c^2 s^2 + 3Rcs + 1}$$

$$BA(j\omega) = \frac{A_V R C (j\omega)}{1 - \omega^2 R^2 C^2 + j\omega \cdot (3RC)}$$

$$\begin{cases} |BA(j\omega_0)| = 1 & 1 - \omega_0^2 R^2 C^2 = 0 \\ \angle BA(j\omega_0) = 0 & \omega_0 = \frac{1}{RC} \end{cases}$$

$$BA(j\omega_0) = \frac{A_V}{3} = \left(1 + \frac{R_2}{R_1}\right) \cdot \frac{1}{3}$$

13 gennaio 2014

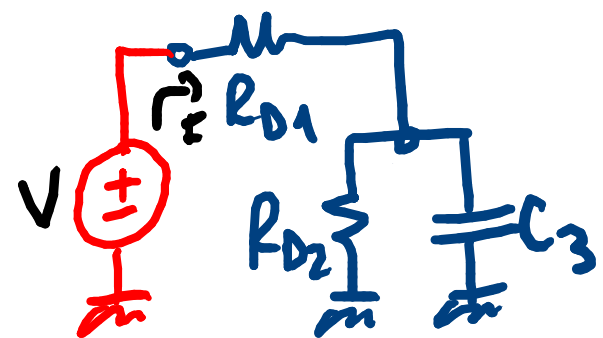


$$A_v(s) = \frac{V_o}{V_{in}} = \frac{A_{vo} s (s + \omega_{o2}) (s + \omega_{o3})}{(s + \omega_{p1}) (s + \omega_{p2}) (s + \omega_{p3})}$$

$$A_{vo} = -\frac{g_m R_{D1}}{1 + g_m R_2} \quad \omega_{p2} = \frac{1}{C_1 R_G} = 40 \text{ rad/s}$$

$$\omega_{p2} = \frac{1}{C_2 R_{vc2}} \quad R_{vc2} = R_1 \parallel \left[R_2 + \frac{1}{g_m} \right]$$

$$\omega_{o2} = \frac{1}{2\pi C_2} \quad \omega_{p3} = \frac{1}{C_3 \cdot R_{vc3}} \quad R_{vc3} = R_{D2}$$

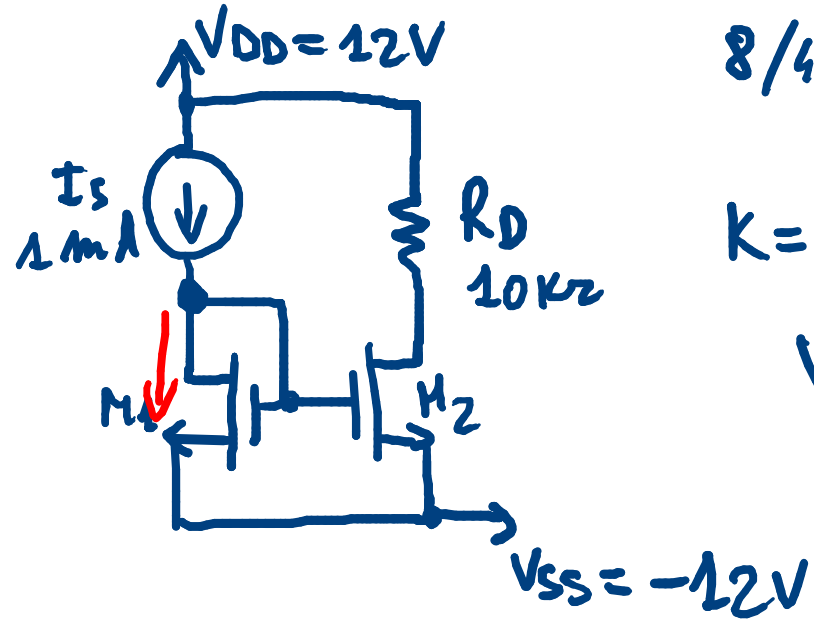


$$Z = \frac{V}{I} \quad Z = \frac{1}{Y}$$

$$Y = \frac{I}{V}$$

$$\omega_{p4} = \omega_{o2} = \frac{1}{C_3 \cdot R_{D1} \parallel R_{D2}} = \omega_{o3}$$

8/4/2013



$$K = \mu_n C_{ox} \frac{W}{L} = 1 \text{ mA/V}^2$$

$$V_T = 1 \text{ V}$$

$$I_{DS1} = I_S \quad I_{DS1} = \frac{K}{2} (V_{GS1} - V_T)^2 = I_S$$

$$V_{GS} = \pm \sqrt{\frac{2I_S}{K}} + V_T = \begin{cases} 2.414 \geq V_T \\ -4.14 \text{ mV} \end{cases}$$

$$V_{DS1} = V_{GS1} \gg V_{GS1} - V_T = 1.414 \text{ V}$$

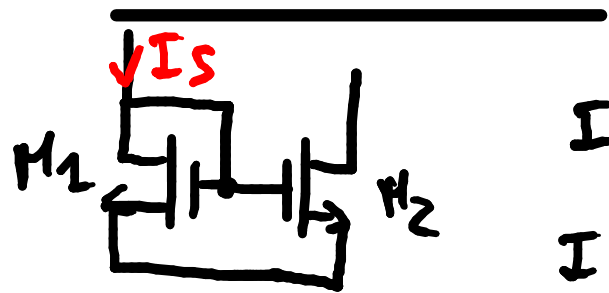
$$V_{GS1} = V_{GS2} \Rightarrow I_{DS1} = I_{DS2} = 1 \text{ mA}$$

$$V_{DS2} = V_{D2} - V_{S2} = V_{DD} - R_D I_{DS2} - V_{SS} =$$

$$V_{DS2} = 14 \text{ V} \gg V_{GS2} - V_T = 1.414 \text{ V}$$

$$V_{DD} - R_D I_S - V_{SS} \gg V_{GS2} - V_T$$

$$\frac{V_{DD} - V_{SS} + V_T - V_{GS}}{I_S} \gg R_D$$



$$I_{DS1} = \frac{K_1}{2} (V_{GS1} - V_T)^2$$

$$I_{DS2} = \frac{K_2}{2} (V_{GS2} - V_T)^2$$

$$V_{GS1} = V_{GS2}$$

$$\frac{I_{DS1}}{I_{DS2}} = \frac{\frac{K_1}{2} (V_{GS1} - V_T)^2}{\frac{K_2}{2} (V_{GS2} - V_T)^2} = \frac{K_1}{K_2}$$